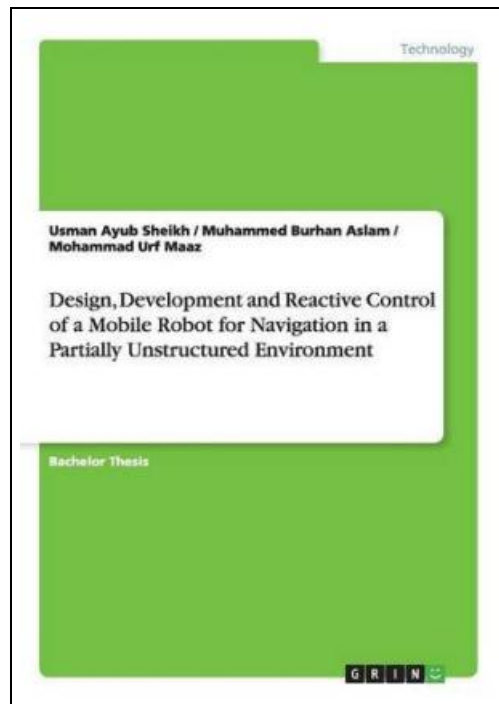


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DESIGN, DEVELOPMENT AND REACTIVE CONTROL OF A MOBILE ROBOT FOR NAVIGATION IN A PARTIALLY UNSTRUCTURED ENVIRONMENT



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