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# NONLINEAR CONTROL OF VEHICLES AND ROBOTS (HARDBACK)



Springer London Ltd, United Kingdom, 2011. Hardback Condition: New. 2011. Language: English . Brand New Book. Nonlinear Control of Vehicles and Robots develops a unified approach to the dynamic modeling of robots in terrestrial, aerial and marine environments. The main classes of nonlinear systems and stability methods are summarized and basic nonlinear control methods, useful in manipulator and vehicle control, are presented. Formation control of ground robots and ships is discussed. The book also deals with the modeling and control..

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- Authored by Béla Lantos, Lorinc Márton
- Released at 2011



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