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Condition New. Publisher/Verlag: LAP Lambert Academic Publishing | Theory and Robotic Experiments | This thesis presents methods, techniques and architectures to build intelligent control systems. The Kalman filter potentialities are extended to several domains, such as robust adaptive control, data fusion and fuzzy learning. The main contributions are: 1) The introduction of stochastic active observers. Model reference adaptive control is achieved through Kalman filtering techniques. 2) Applying stochastic active observers, a six degrees of freedom compliant motion controller is designed...

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