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MODELS AND ALGORITHMS FOR ONLINE EXPLORATION AND SEARCH



Shaker Verlag Apr 2011, 2011. Buch Book Condition Neu. 24x17x cm. Neuware - This work considers some algorithmic aspects of exploration and search, two tasks that arise, for example, in the field of motion planning for autonomous mobile robots. We assume that the environment is not known to the robot in advance, so we deal with online algorithms. First, we consider a special kind of environments that we call cellular environments, where the robot's surrounding is subdivided by an integer...

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- Authored by Tom Kamphans
- Released at 2011



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